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Robotics gives engineering
students and practicing
engineers the information
needed to design a robot, to
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appropriate applications, or

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to analyze a robot. The updated third edition contains many new subjects and the content has been streamlined throughout the text.

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that is concerned predominantly with mechanics has a brief section devoted to computational considerations. This book evolved from class notes

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Control principles developed
in lectures.

16-311 Introduction to
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This course provides a
mathematical introduction to

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the mechanics and control of robots that can be modeled as kinematic chains. Topics covered include the concept of a robot's configuration space and degrees of freedom, static grasp analysis, the description of

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Control rigid body motions,
kinematics of open and
closed chains, and the
basics of robot control.

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For senior-year or first-year graduate level robotics courses generally taught from the mechanical engineering, electrical engineering, or computer science departments. Since its original publication in

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Control debe situarse un punto básico. The results of C-space map, which are derived by the modified analysis, prove the accuracy of the overall C-space mapping and construction, and then a successful and guaranteed

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path from a start to goal
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"Computational Principles of
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not have the room to
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